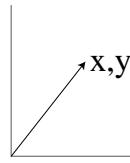
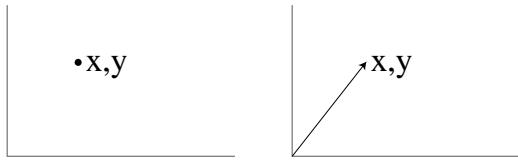


mas110: recitation 0: vectors

vectors (points)

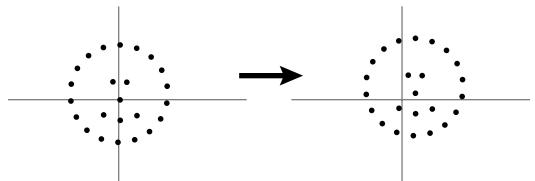
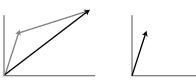
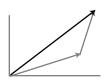
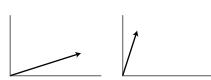
$$V = \begin{bmatrix} x \\ y \end{bmatrix}$$



addition (translation)

$$\begin{bmatrix} x_1 \\ y_1 \end{bmatrix} + \begin{bmatrix} x_2 \\ y_2 \end{bmatrix} = \begin{bmatrix} x_1+x_2 \\ y_1+y_2 \end{bmatrix} = \begin{bmatrix} x_2+x_1 \\ y_2+y_1 \end{bmatrix} = \begin{bmatrix} x_2 \\ y_2 \end{bmatrix} + \begin{bmatrix} x_1 \\ y_1 \end{bmatrix}$$

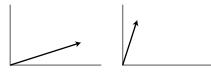
$$U + V = W = W = V + U$$



subtraction (difference)

$$\begin{bmatrix} x_1 \\ y_1 \end{bmatrix} - \begin{bmatrix} x_2 \\ y_2 \end{bmatrix} = \begin{bmatrix} x_1-x_2 \\ y_1-y_2 \end{bmatrix} \neq \begin{bmatrix} x_2-x_1 \\ y_2-y_1 \end{bmatrix} = \begin{bmatrix} x_2 \\ y_2 \end{bmatrix} - \begin{bmatrix} x_1 \\ y_1 \end{bmatrix}$$

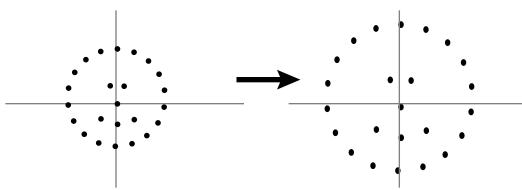
$$U - V = W_0 \neq W_1 = V - U$$



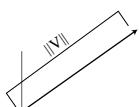
multiplication (scaling)

$$a \begin{bmatrix} x_1 \\ y_1 \end{bmatrix} = \begin{bmatrix} ax_1 \\ ay_1 \end{bmatrix}$$

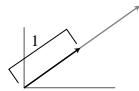
$$aV = W$$



distance: $\sqrt{x^2+y^2} = \|V\|$



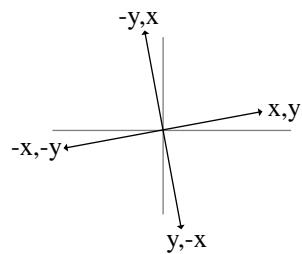
normalization: $\hat{U} = \frac{U}{\|U\|}$ \hat{U} is a unit vector, $\|\hat{U}\| = 1$



parallel & perpendicular

$$\begin{bmatrix} x \\ y \end{bmatrix} \parallel \begin{bmatrix} -x \\ -y \end{bmatrix} \perp \begin{bmatrix} y \\ -x \end{bmatrix} \parallel \begin{bmatrix} -y \\ x \end{bmatrix}$$

$$U \parallel -U \perp V \parallel -V$$



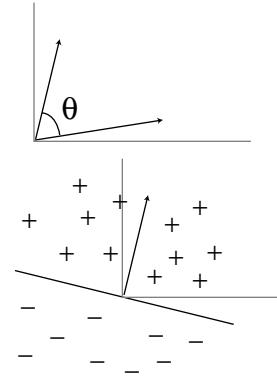
dot product

$$\begin{bmatrix} x_1 \\ y_1 \end{bmatrix} \cdot \begin{bmatrix} x_2 \\ y_2 \end{bmatrix} = x_1 x_2 + y_1 y_2$$

$$U \cdot V = \cos(\theta) \|U\| \|V\| \quad \frac{U \cdot V}{\|U\| \|V\|} = \cos(\theta)$$

If $U \perp V$, then $U \cdot V = 0$

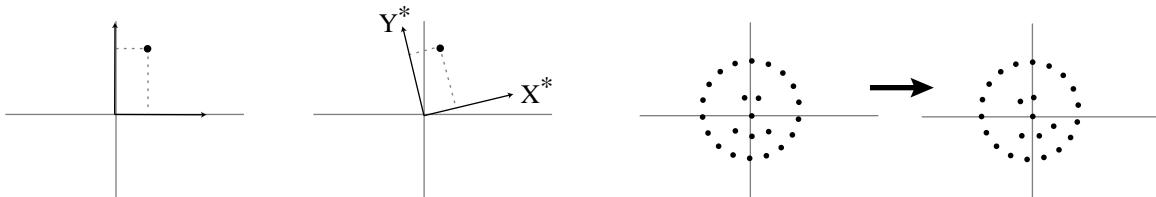
If $U \parallel V$, then $U \cdot V = \|U\| \|V\|$ or $-\|U\| \|V\|$



rotation

$$\begin{aligned} X^* &= \begin{bmatrix} \cos(\theta) \\ \sin(\theta) \end{bmatrix} & [x_1] @ \theta &= x_1 X^* + y_1 Y^* = \begin{bmatrix} x_1 \cos(\theta) - y_1 \sin(\theta) \\ x_1 \sin(\theta) + y_1 \cos(\theta) \end{bmatrix} \\ Y^* &= \begin{bmatrix} -\sin(\theta) \\ \cos(\theta) \end{bmatrix} \end{aligned}$$

$$V @ \theta = [X^* \ Y^*] V = \begin{bmatrix} \cos(\theta) & -\sin(\theta) \\ \sin(\theta) & \cos(\theta) \end{bmatrix} V$$



interpolation

for $k=0$ to n ($n+1$ steps)

$$\begin{bmatrix} x_k \\ y_k \end{bmatrix} = \frac{k}{n} \begin{bmatrix} x_s \\ y_s \end{bmatrix} + \frac{n-k}{n} \begin{bmatrix} x_f \\ y_f \end{bmatrix}$$

